

Multi-task Online Learning for Probabilistic Load Forecasting

Onintze Zaballa, Verónica Álvarez and Santiago Mazuelas
ozaballa@bcamath.org

December 18, 2024



Machine learning algorithms for load forecasting



Santiago Mazuelas



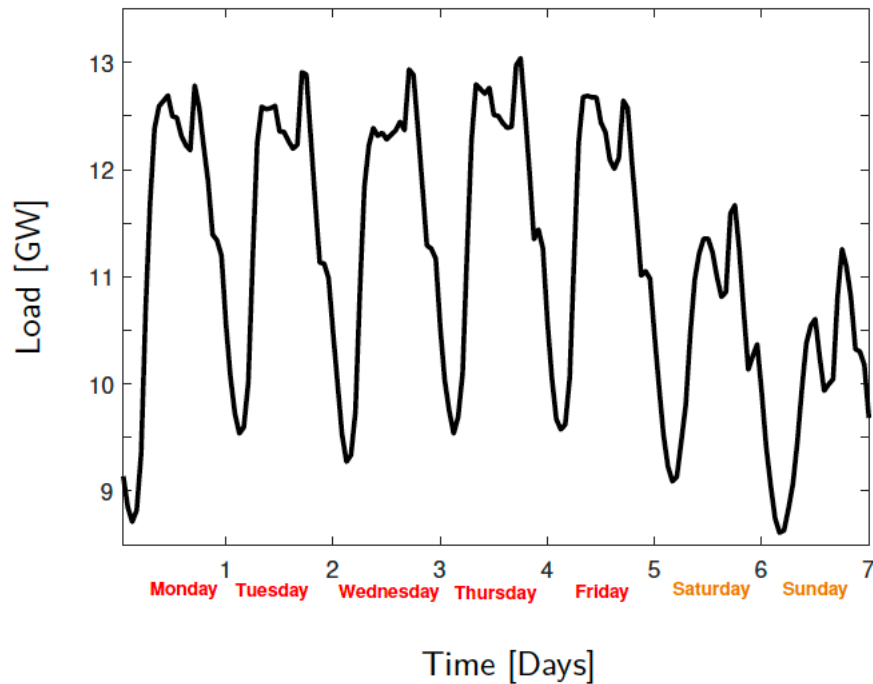
Verónica Álvarez



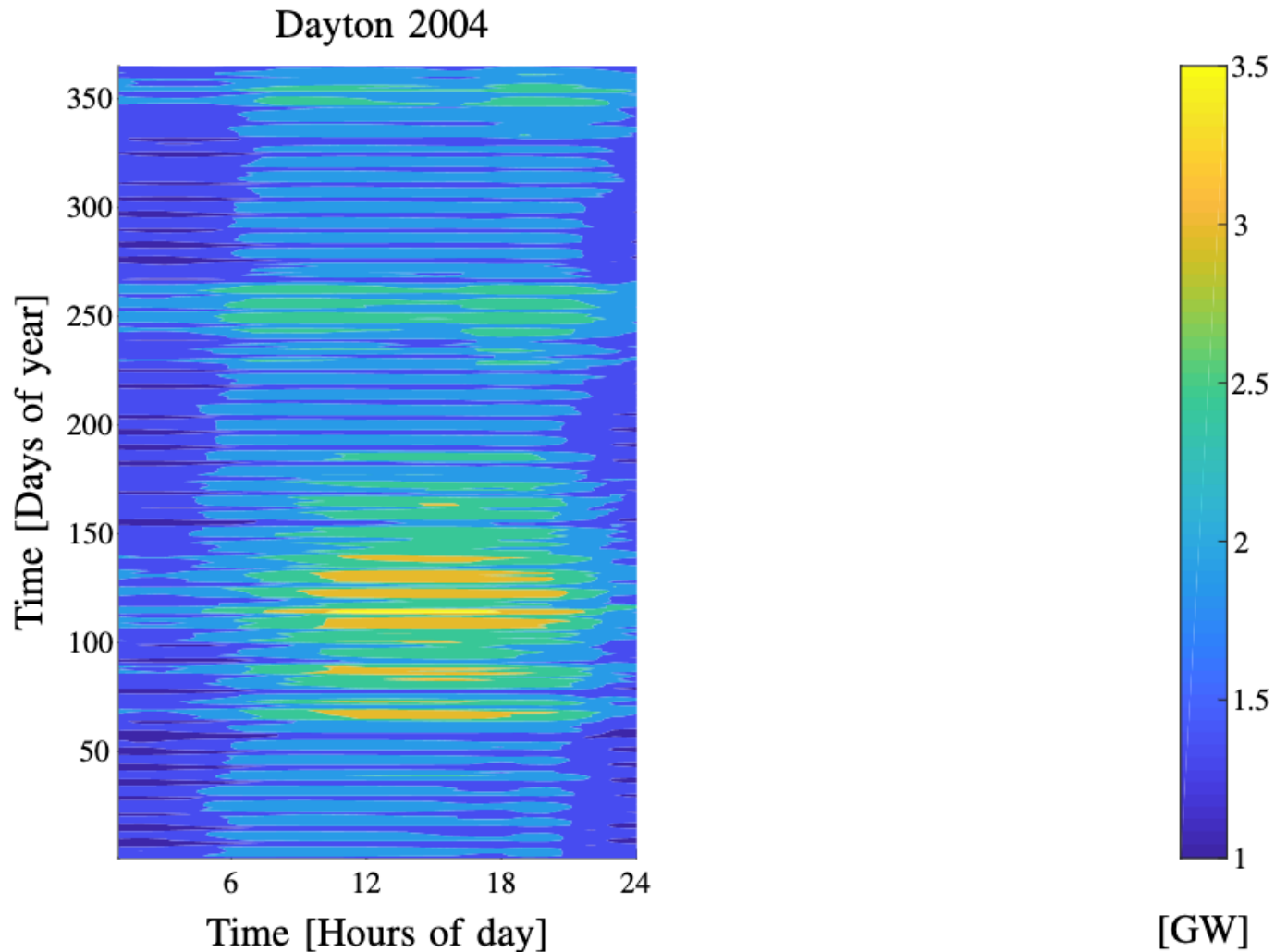
Onintze Zaballa

Load forecasting

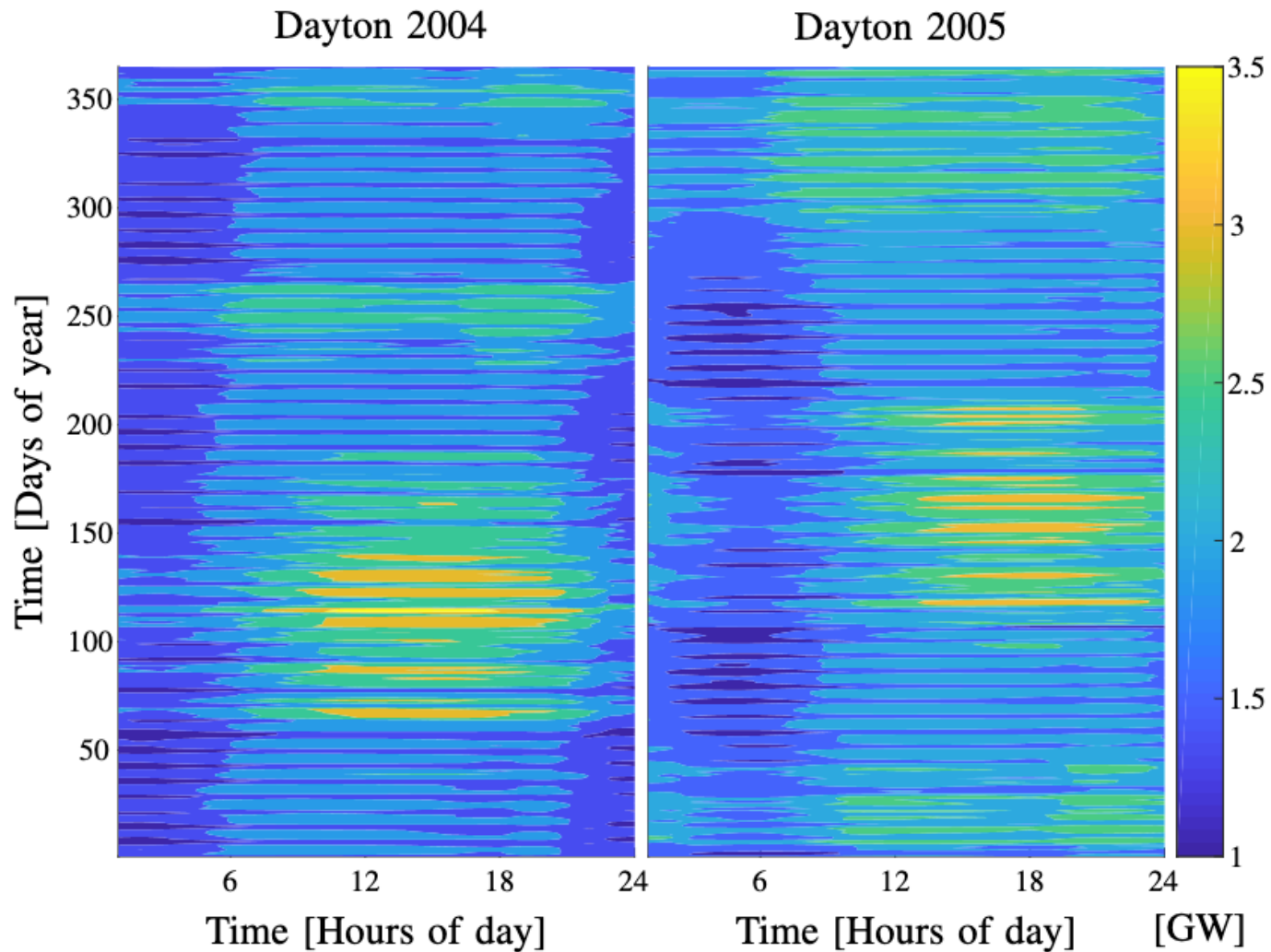
- Load forecasting is important for energy management tasks
- Forecasting methods exploit consumption patterns influenced by multiple factors such as hours of the day, holidays, or weather conditions
- Energy demand is uncertain due to consumer behaviors or unexpected events



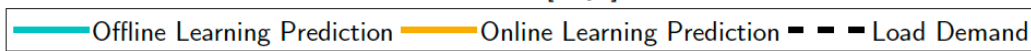
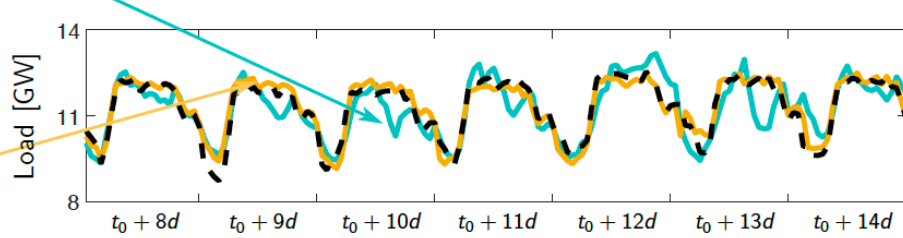
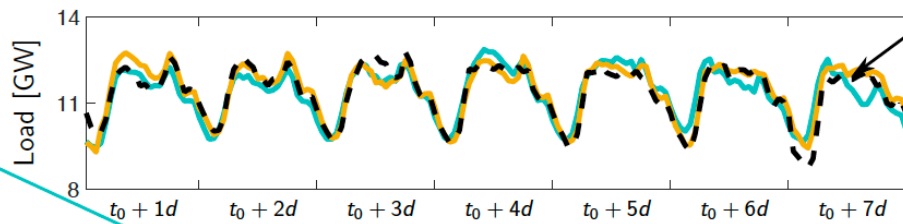
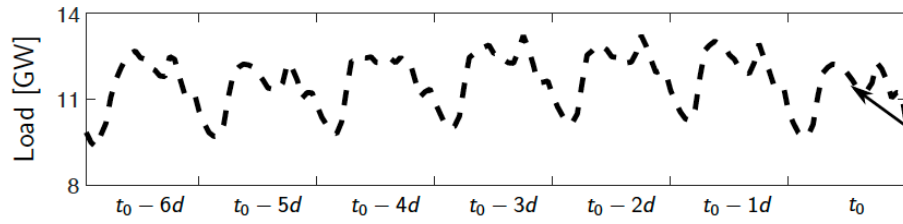
Load consumption patterns change over time



Load consumption patterns change over time



Online learning



Methods based on offline learning cannot accommodate to such changes

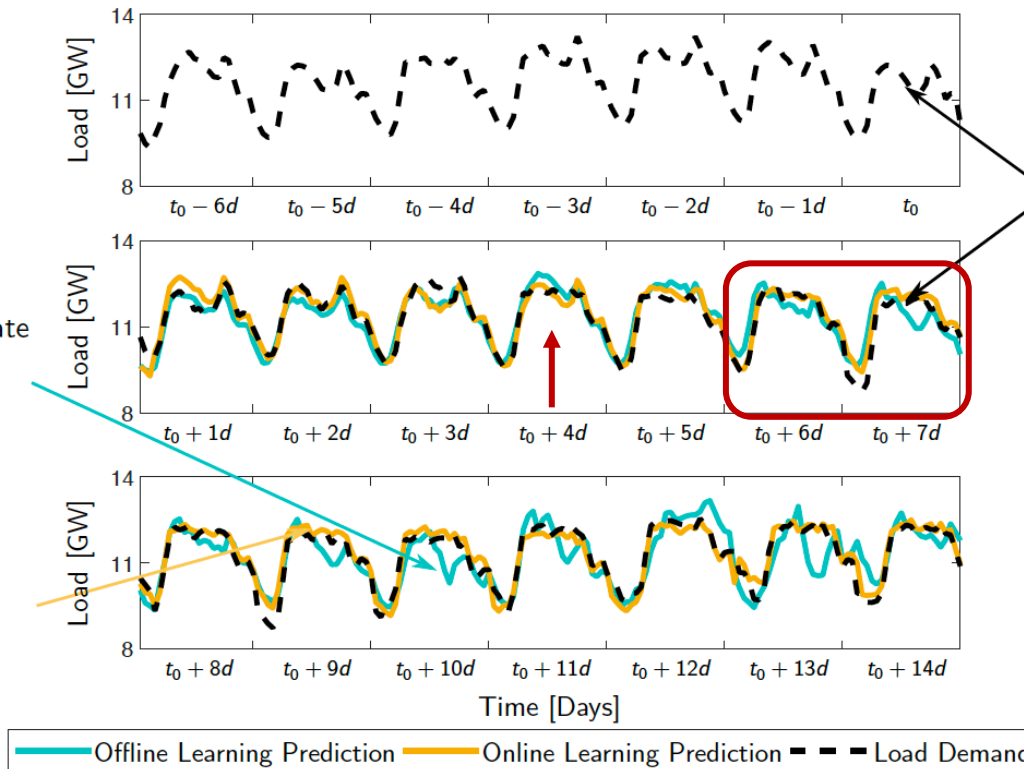
Methods based on online learning correctly adapt models after few days

Consumptions change from a two-peak pattern to a flatter pattern

Online learning

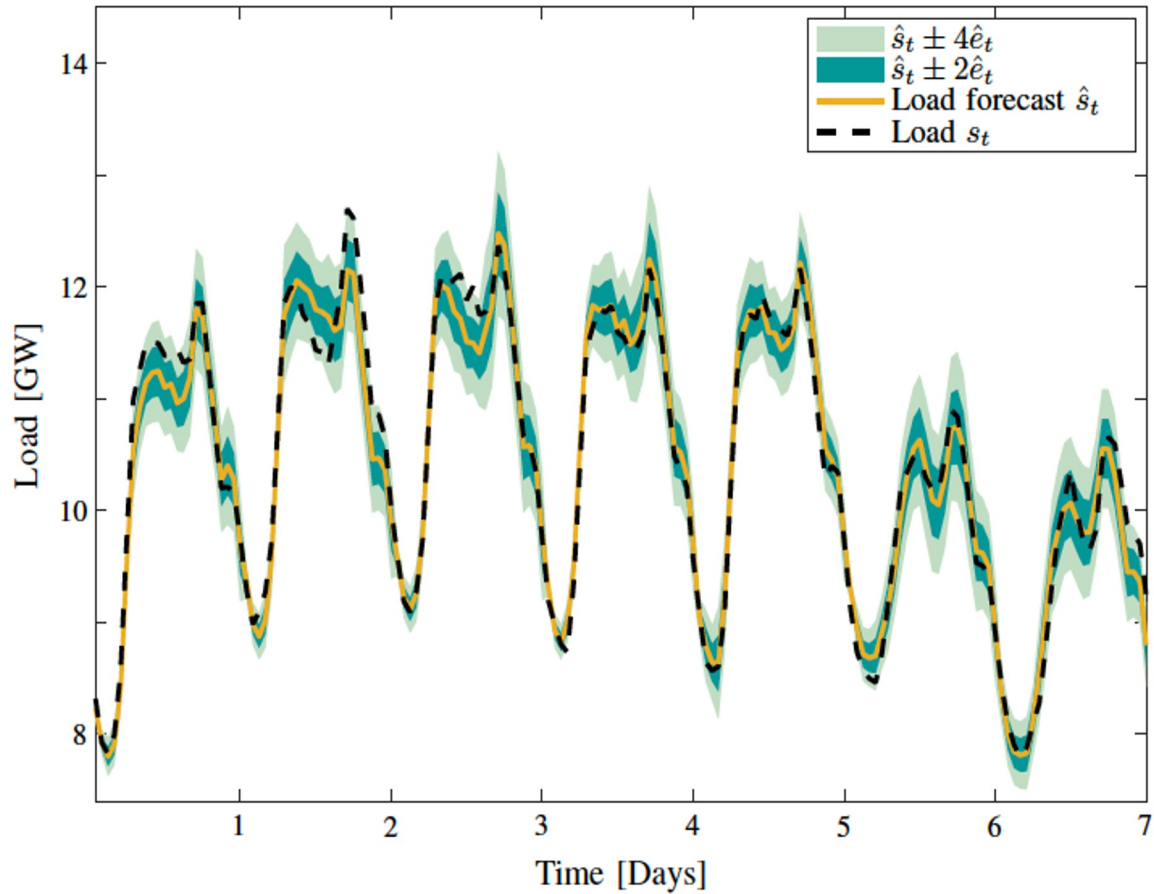
Methods based on offline learning cannot accommodate to such changes

Methods based on online learning correctly adapt models after few days



Consumptions change from a two-peak pattern to a flatter pattern

Probabilistic forecasting techniques



Outline

- Introduction and motivation
- Problem formulation
- Models and theoretical results
- Extension to high-dimensional models
- Experimental results
- Conclusions

Outline

- Introduction and motivation
- Problem formulation

Problem formulation

Forecasting algorithms obtain a vector of L forecasts corresponding with future loads

$$\hat{\mathbf{y}} = [\hat{s}_{t+1}, \hat{s}_{t+2}, \dots, \hat{s}_{t+L}]^\top$$

given an instance vector of past loads and observations related to future loads

$$\mathbf{x} = [s_{t-m}, \dots, s_t, \mathbf{r}_{t+1}^\top, \dots, \mathbf{r}_{t+L}^\top]^\top, m < t$$

where t is the time when the load is measured.

Problem formulation

Forecasting algorithms obtain a vector of L forecasts corresponding with future loads

$$\hat{\mathbf{y}} = [\hat{s}_{t+1}, \hat{s}_{t+2}, \dots, \hat{s}_{t+L}]^\top$$

given an instance vector of past loads and observations related to future loads

$$\mathbf{x} = [s_{t-m}, \dots, s_t, \mathbf{r}_{t+1}^\top, \dots, \mathbf{r}_{t+L}^\top]^\top, m < t$$

where t is the time when the load is measured.

The calendar information

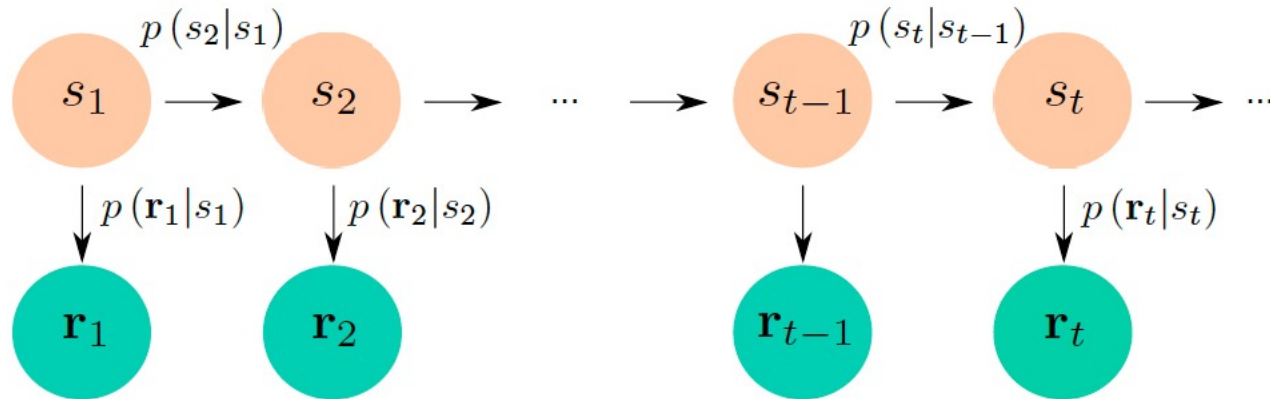
$$c(t) \in \{1, 2, \dots, C\}$$

includes details such as hour of day and holidays.

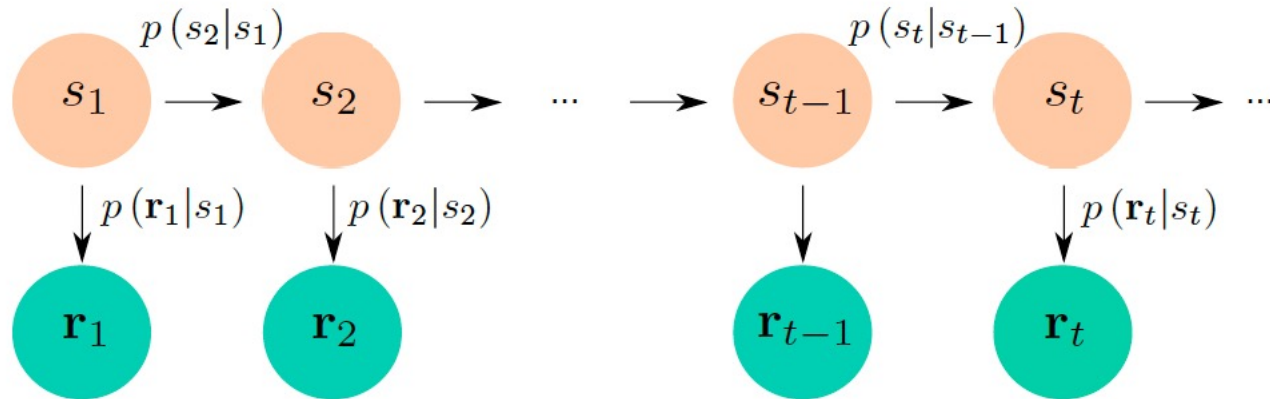
Outline

- Introduction and motivation
- Problem formulation
- Models and theoretical results

Probabilistic Load Forecasting Based on Adaptive Online Learning



Probabilistic Load Forecasting Based on Adaptive Online Learning



Model relationship
consecutive loads

$$p(s_t|s_{t-1}) = N(s_t; \mathbf{u}_s^T \boldsymbol{\eta}_{s,c}, \sigma_{s,c})$$

Model relationship
loads and observations

$$p(\mathbf{r}_t|s_t) \propto p(s_t|\mathbf{r}_t) = N(s_t; \mathbf{u}_r^T \boldsymbol{\eta}_{r,c}, \sigma_{r,c})$$

Learning HMM parameters

The HMM describing is characterized by parameters

$$\Theta = \{\boldsymbol{\eta}_{s,c}, \sigma_{s,c}, \boldsymbol{\eta}_{r,c}, \sigma_{r,c} : c = 1, 2, \dots, C\}$$

Parameters Θ can be obtained by maximizing the weighted log-likelihood given by

$$L_i(\boldsymbol{\eta}, \sigma) = \sum_{j=1}^i \lambda^{i-j} \log N(s_{t_j}; \mathbf{u}_{t_j}^\top \boldsymbol{\eta}, \sigma)$$

with $i \leq n$, $\lambda \in (0, 1)$ and $s_{t_1}, s_{t_2}, \dots, s_{t_n}$ and $\mathbf{u}_{t_1}, \mathbf{u}_{t_2}, \dots, \mathbf{u}_{t_n}$ sequences of loads and corresponding feature vectors with the same calendar type.

Learning HMM parameters

The HMM describing is characterized by parameters

$$\Theta = \{\boldsymbol{\eta}_{s,c}, \sigma_{s,c}, \boldsymbol{\eta}_{r,c}, \sigma_{r,c} : c = 1, 2, \dots, C\}$$

Parameters Θ can be obtained by maximizing the weighted log-likelihood given by

$$L_i(\boldsymbol{\eta}, \sigma) = \sum_{j=1}^i \lambda^{i-j} \log N(s_{t_j}; \mathbf{u}_{t_j}^\top \boldsymbol{\eta}, \sigma)$$

with $i \leq n$, $\lambda \in (0, 1)$ and $s_{t_1}, s_{t_2}, \dots, s_{t_n}$ and $\mathbf{u}_{t_1}, \mathbf{u}_{t_2}, \dots, \mathbf{u}_{t_n}$ sequences of loads and corresponding feature vectors with the same calendar type.

Online learning of HMM parameters

Theorem

Let $\boldsymbol{\eta}_i^* \in \mathbb{R}^K$, $\sigma_i^* \in \mathbb{R}$ parameters that maximize the weighted log-likelihood.
If parameters $\boldsymbol{\eta}_i \in \mathbb{R}^K$, $\sigma_i \in \mathbb{R}$ are given by recursions

$$\boldsymbol{\eta}_i = \boldsymbol{\eta}_{i-1} + \frac{\mathbf{P}_{i-1} \mathbf{u}_{t_i}}{\lambda + \mathbf{u}_{t_i}^T \mathbf{P}_{i-1} \mathbf{u}_{t_i}} (s_{t_i} - \mathbf{u}_{t_i}^T \boldsymbol{\eta}_{i-1}),$$
$$\sigma_i = \sqrt{\sigma_{i-1}^2 - \frac{1}{\gamma_i} \left(\sigma_{i-1}^2 - \frac{\lambda (s_{t_i} - \mathbf{u}_{t_i}^T \boldsymbol{\eta}_{i-1})^2}{\lambda + \mathbf{u}_{t_i}^T \mathbf{P}_{i-1} \mathbf{u}_{t_i}} \right)},$$

with

$$\mathbf{P}_i = \frac{1}{\lambda} \left(\mathbf{P}_{i-1} - \frac{\mathbf{P}_{i-1} \mathbf{u}_{t_i} \mathbf{u}_{t_i}^T \mathbf{P}_{i-1}}{\lambda + \mathbf{u}_{t_i}^T \mathbf{P}_{i-1} \mathbf{u}_{t_i}} \right), \quad \gamma_i = 1 + \lambda \gamma_{i-1},$$

for any $i \leq n$ such that the matrix $\sum_{j=1}^i \lambda^{i-j} \mathbf{u}_{t_j} \mathbf{u}_{t_j}^T$ is not singular.

Probabilistic forecasts

Theorem

If $\{s_t, \mathbf{r}_t\}_{t \geq 1}$ is a HMM characterized by parameters Θ . Then, for $i = 1, 2, \dots, L$

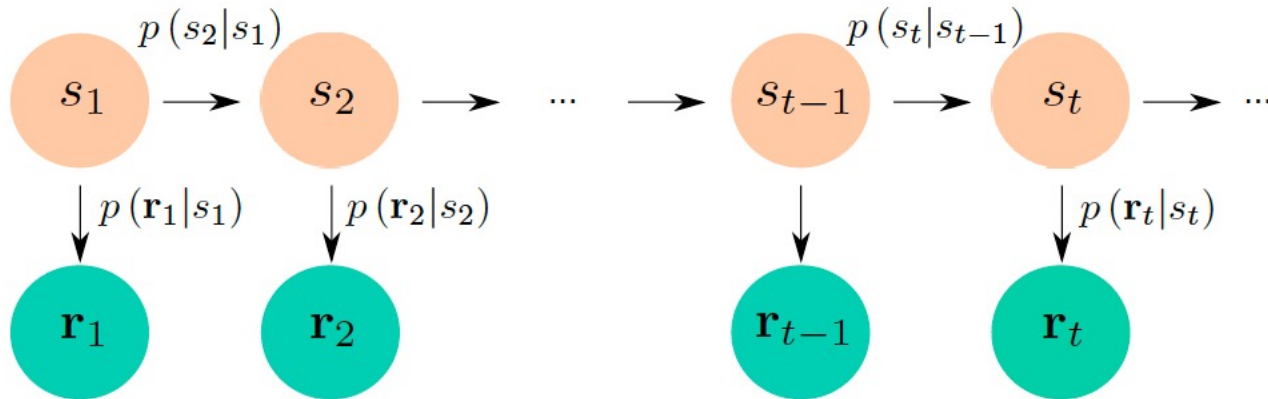
$$p(s_{t+i} | s_t, \mathbf{r}_{t+1}, \dots, \mathbf{r}_{t+i}) = N(s_{t+i}; \hat{s}_{t+i}, \hat{e}_{t+i})$$

where \hat{s}_{t+i} and \hat{e}_{t+i} can be computed by the following recursions

$$c = c(t+i), \hat{\mathbf{u}}_s = [1, \hat{s}_{t+i-1}]^T, \mathbf{u}_r = u_r(\mathbf{r}_{t+i})$$
$$\hat{s}_{t+i} = \frac{\hat{\mathbf{u}}_s^T \boldsymbol{\eta}_{s,c} \sigma_{r,c}^2 + \mathbf{u}_r^T \boldsymbol{\eta}_{r,c} \left(\sigma_{s,c}^2 + ([0, 1] \boldsymbol{\eta}_{s,c})^2 \hat{e}_{t+i-1}^2 \right)}{\sigma_{r,c}^2 + \sigma_{s,c}^2 + ([0, 1] \boldsymbol{\eta}_{s,c})^2 \hat{e}_{t+i-1}^2}$$
$$\hat{e}_{t+i} = \sqrt{\frac{\left(\sigma_{s,c}^2 + ([0, 1] \boldsymbol{\eta}_{s,c})^2 \hat{e}_{t+i-1}^2 \right) \sigma_{r,c}^2}{\sigma_{r,c}^2 + \sigma_{s,c}^2 + ([0, 1] \boldsymbol{\eta}_{s,c})^2 \hat{e}_{t+i-1}^2}}$$

for $i = 1, 2, \dots, L$, and $\hat{s}_t = s_t$, $\hat{e}_t = 0$.

Probabilistic Load Forecasting Based on Adaptive Online Learning



Model relationship
consecutive loads

$$p(s_t|s_{t-1}) = N(s_t; \mathbf{u}_s^T \boldsymbol{\eta}_{s,c}, \sigma_{s,c})$$

Model relationship
loads and observations

$$p(\mathbf{r}_t|s_t) \propto p(s_t|\mathbf{r}_t) = N(s_t; \mathbf{u}_r^T \boldsymbol{\eta}_{r,c}, \sigma_{r,c})$$

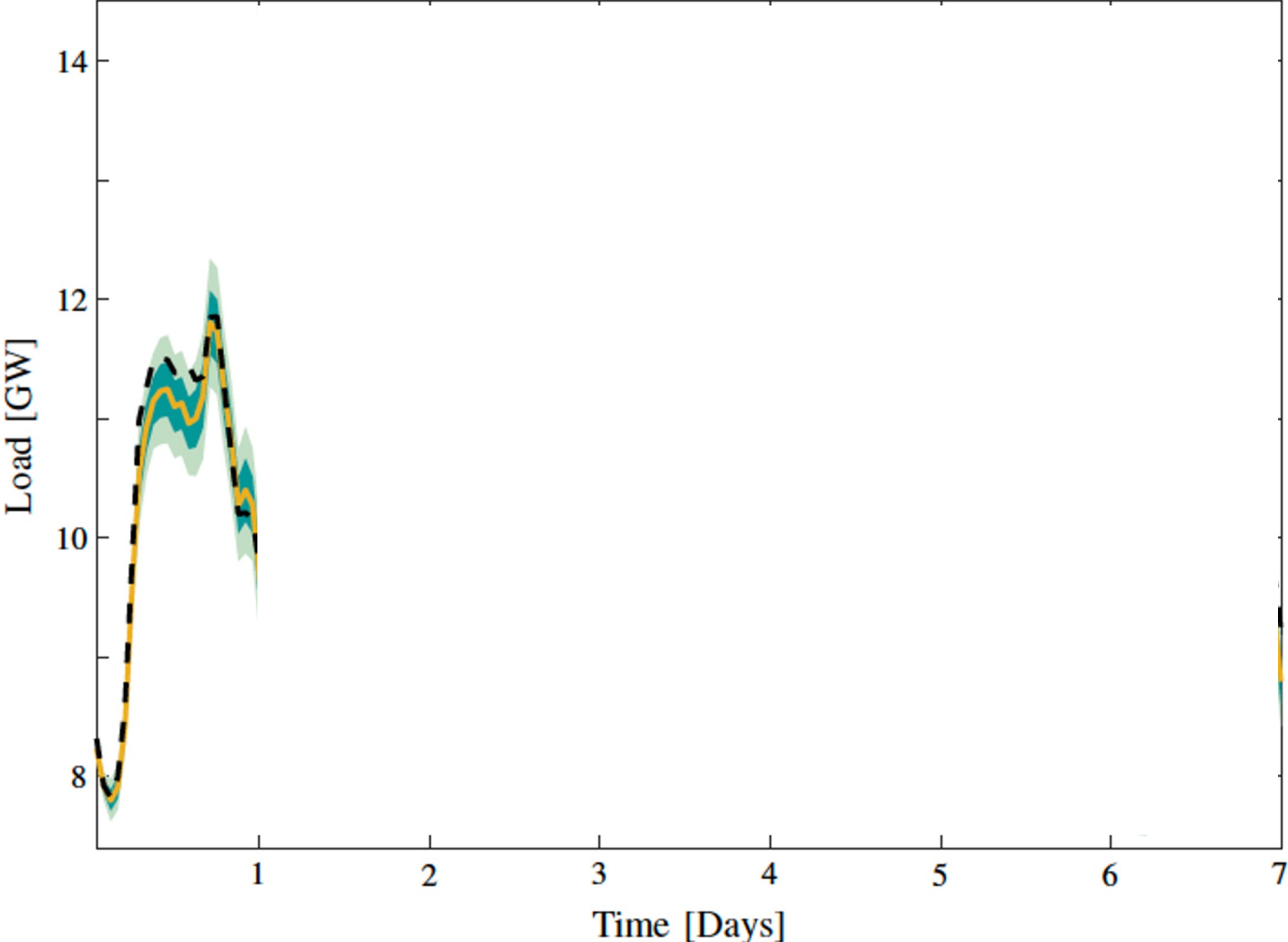
Online learning

$$\boldsymbol{\eta}_i = \boldsymbol{\eta}_{i-1} + \frac{\mathbf{P}_{i-1} \mathbf{u}_{t_i}}{\lambda + \mathbf{u}_{t_i}^T \mathbf{P}_{i-1} \mathbf{u}_{t_i}} (s_{t_i} - \mathbf{u}_{t_i}^T \boldsymbol{\eta}_{i-1})$$

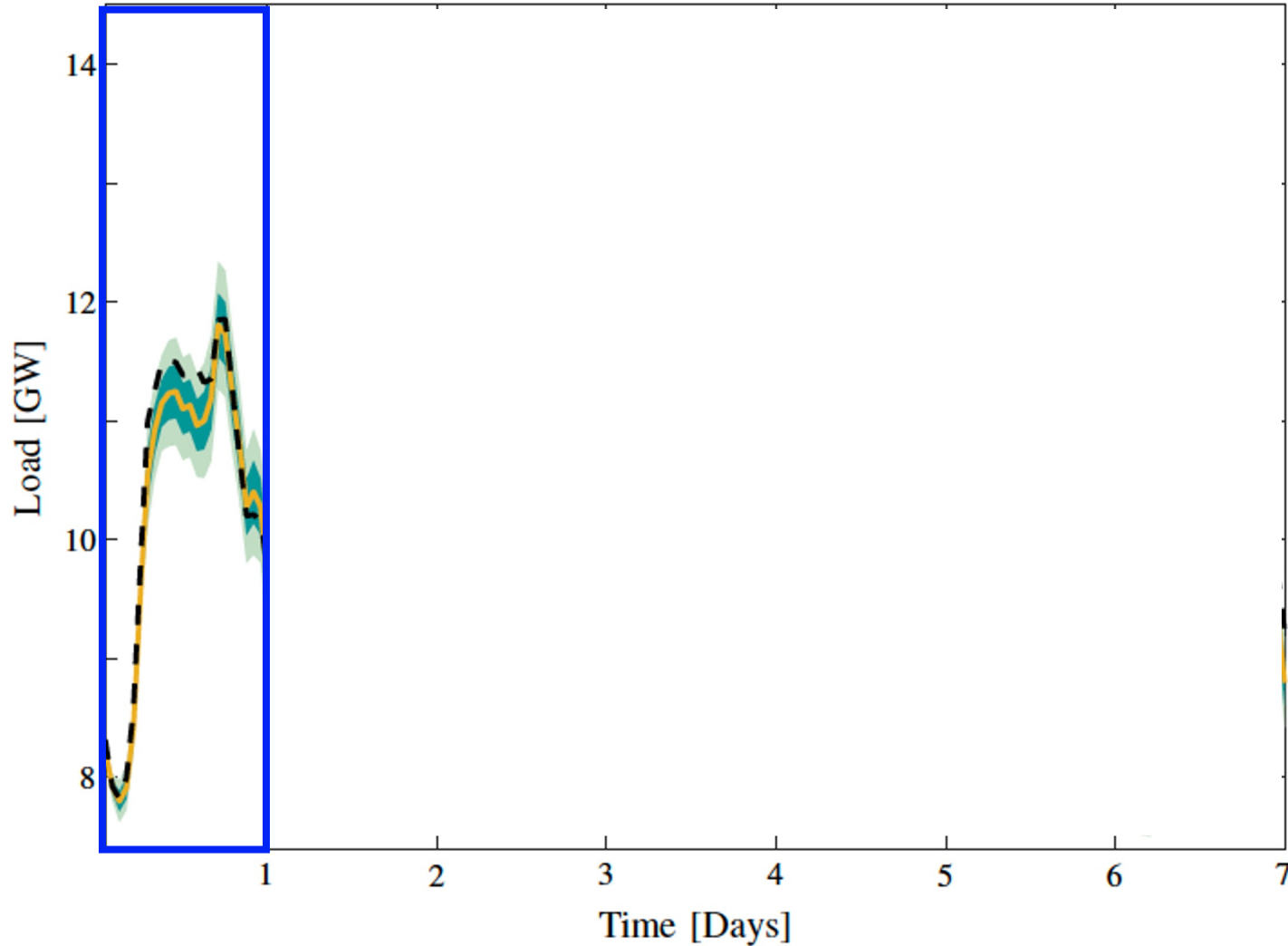
Probabilistic forecasts

$$p(s_{t+i}|s_t, \mathbf{r}_{t+1}, \dots, \mathbf{r}_{t+i}) = N(s_{t+i}; \hat{s}_{t+i}, \hat{e}_{t+i})$$

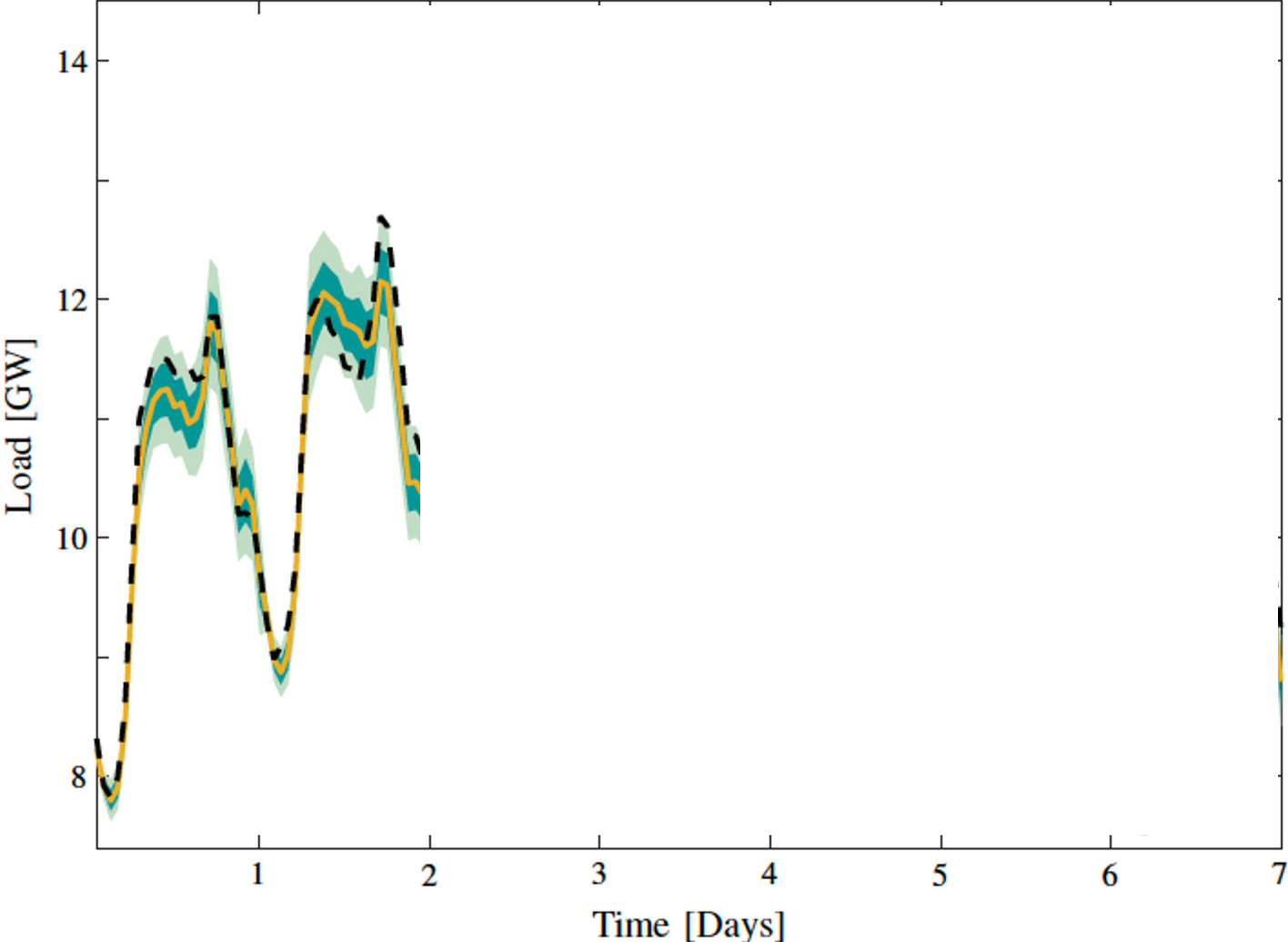
Load forecasting in real-time



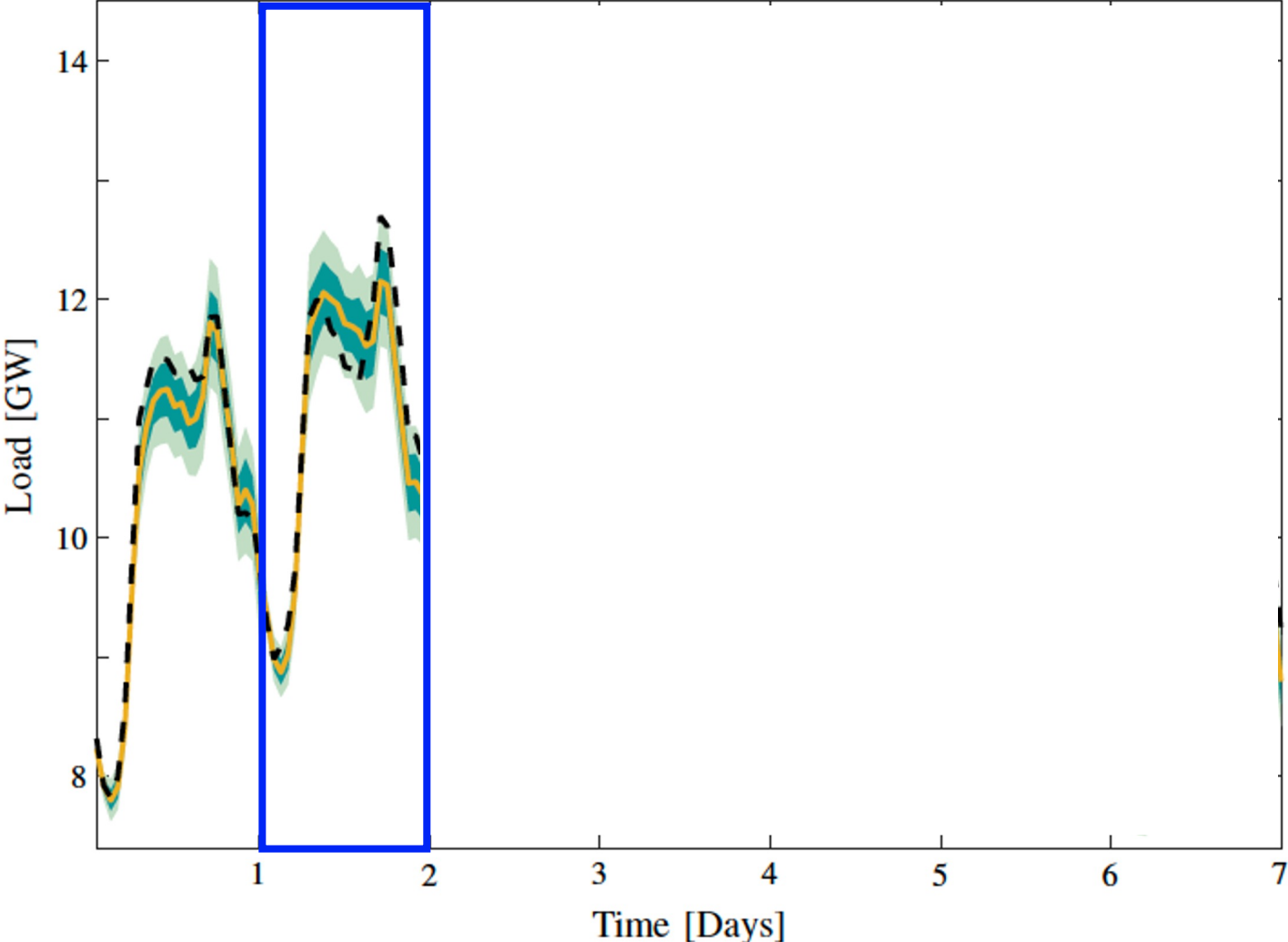
Load forecasting in real-time



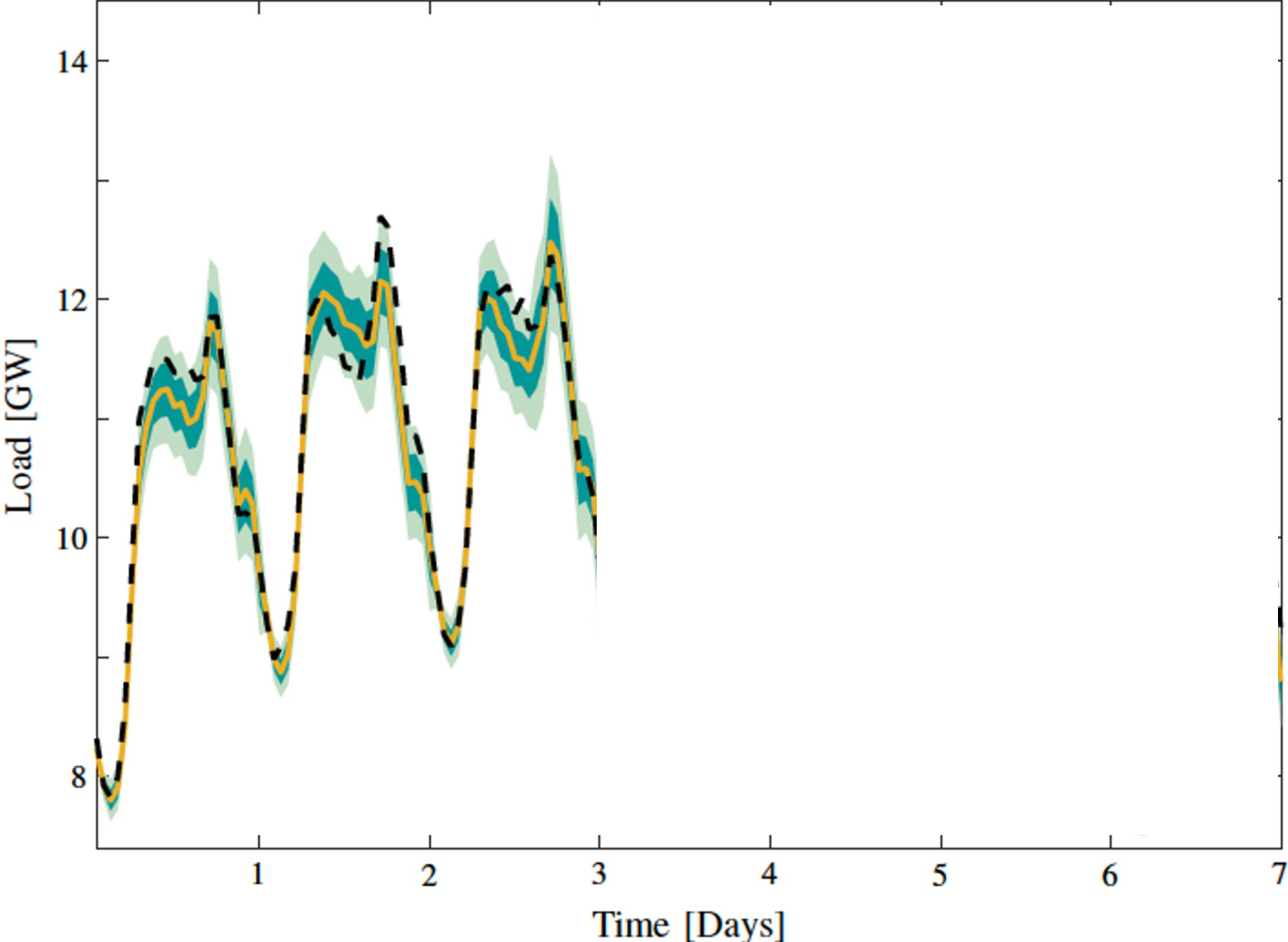
Load forecasting in real-time



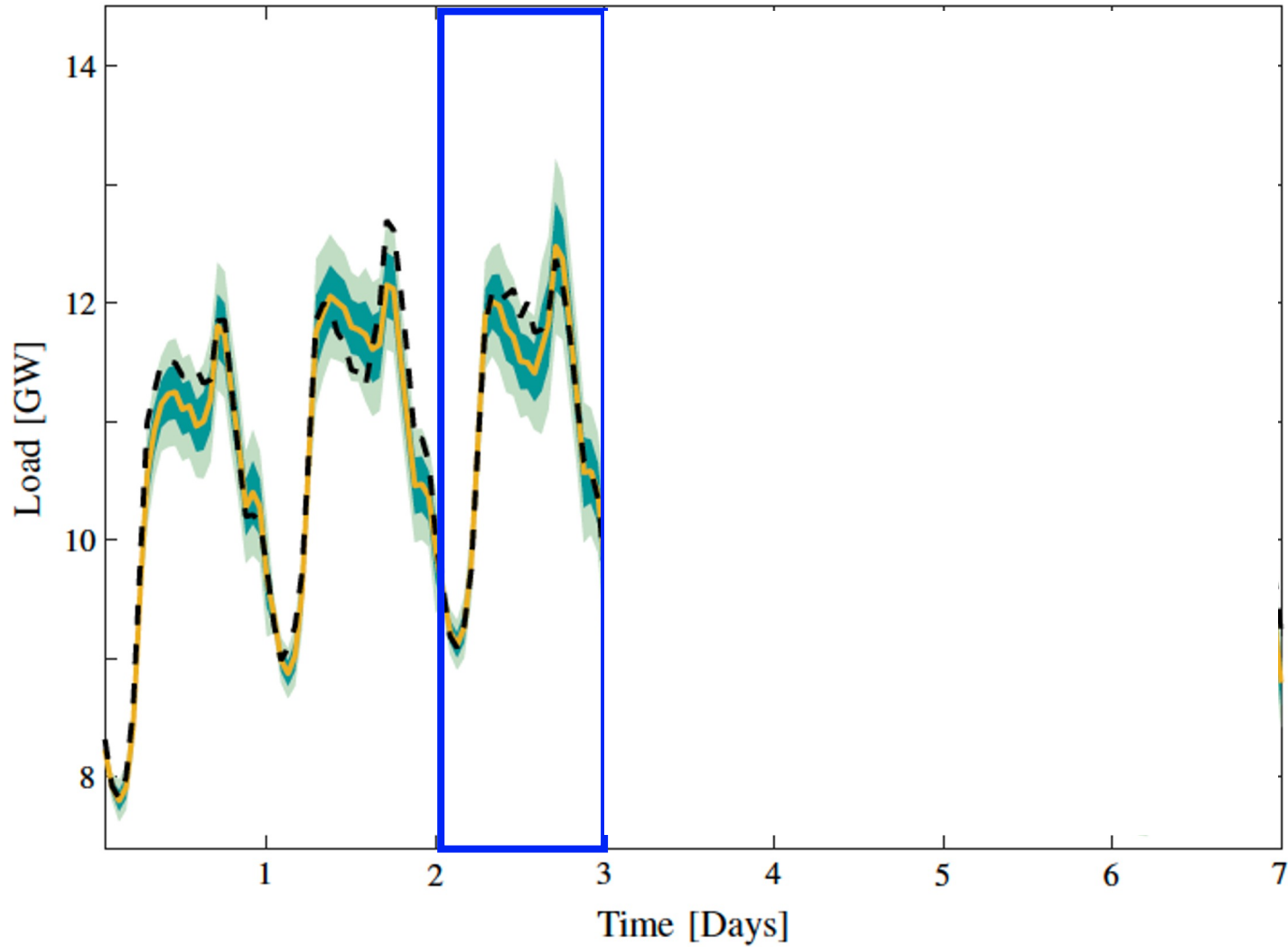
Load forecasting in real-time



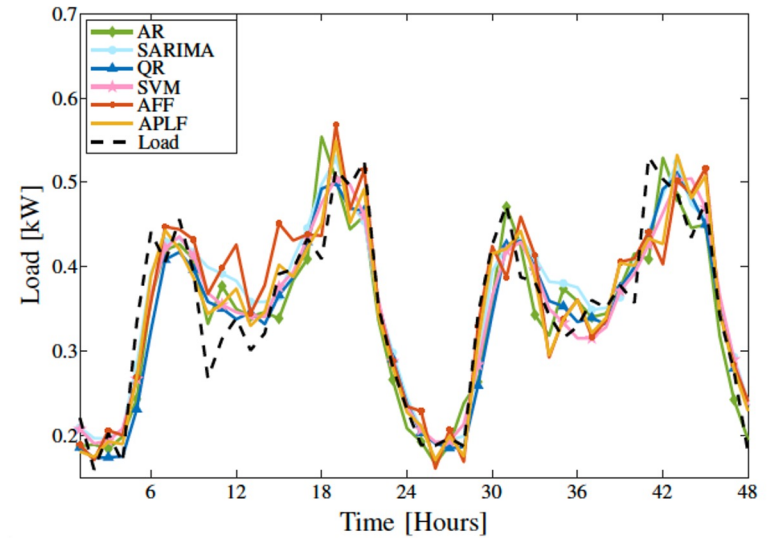
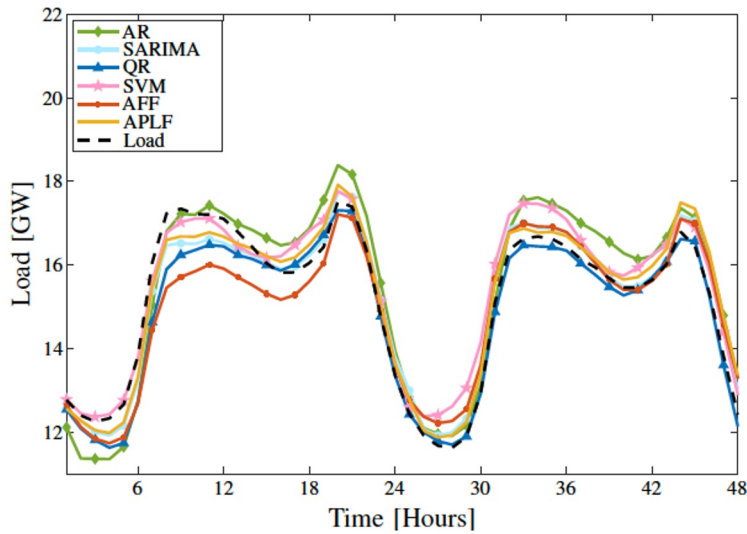
Load forecasting in real-time



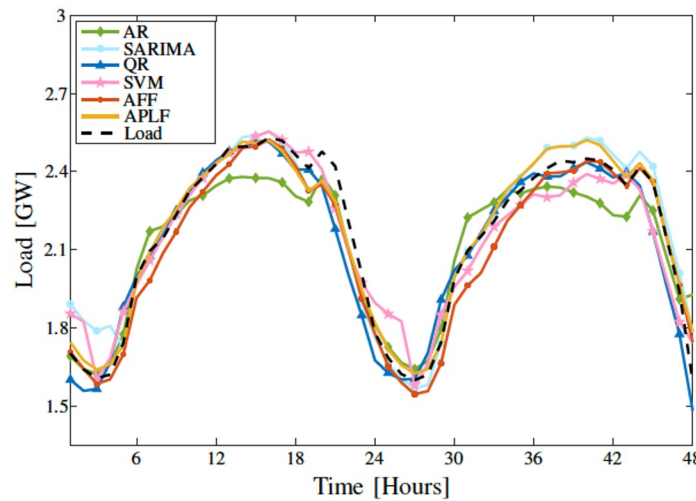
Load forecasting in real-time



Forecasting in different regions



New
England



100
buildings

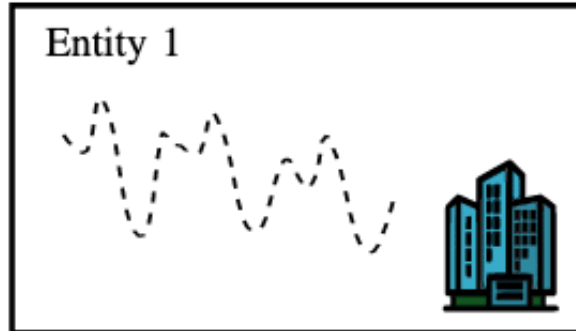
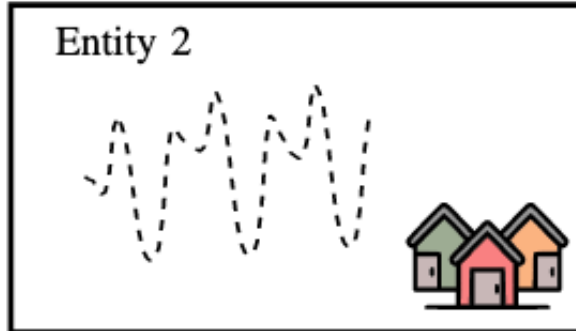
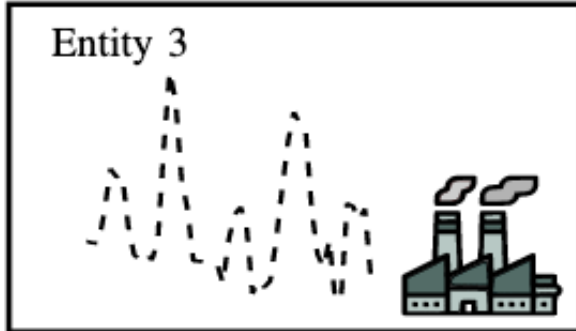
Dayton

Outline

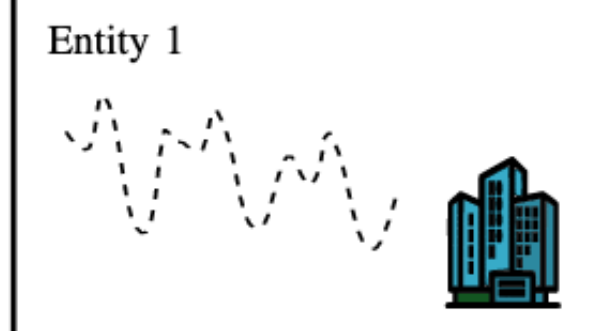
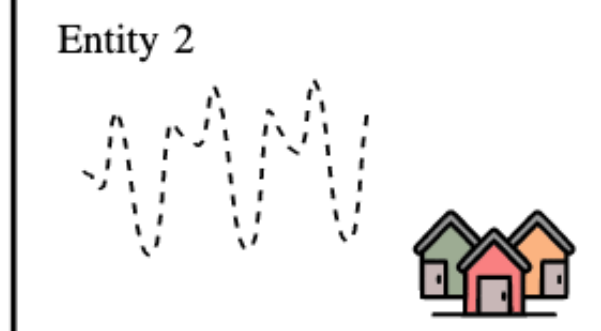
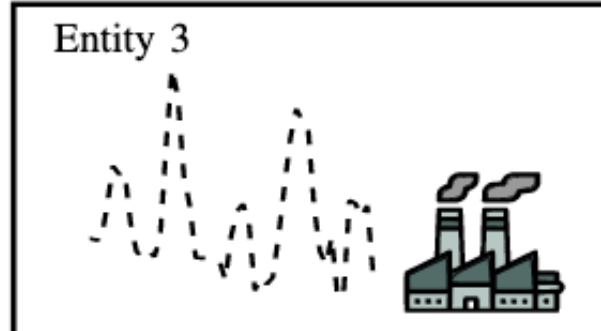
- Introduction and motivation
- Problem formulation
- Models and theoretical results
- Extension to high-dimensional models

Multi-task learning techniques

Single-task learning



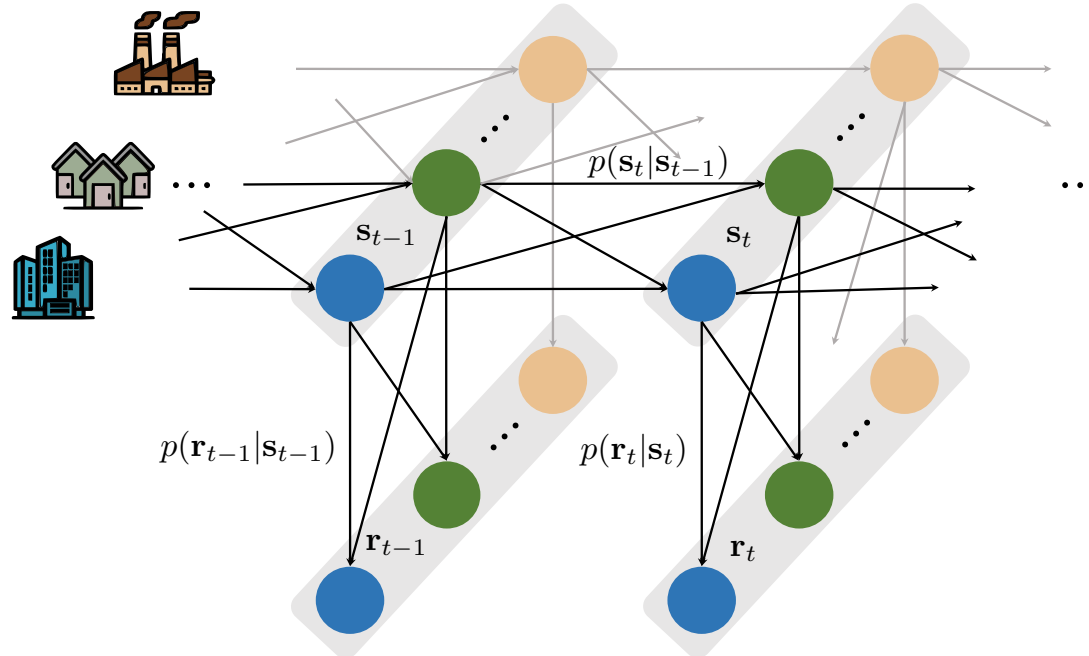
Multi-task learning



Multi-task Hidden Markov model

Hidden Markov Model characterized by the following Gaussian distributions:

$$p(\mathbf{s}_t | \mathbf{s}_{t-1}) = \mathcal{N}(\mathbf{s}_t; \mathbf{M}_{s,c} \mathbf{u}_s, \mathbf{\Sigma}_{s,c}) \quad \text{Loads}$$
$$p(\mathbf{r}_t | \mathbf{s}_t) \propto p(\mathbf{s}_t | \mathbf{r}_t) = \mathcal{N}(\mathbf{s}_t; \mathbf{M}_{r,c} \mathbf{u}_r, \mathbf{\Sigma}_{r,c}) \quad \text{Observations}$$



Multi-task Hidden Markov model

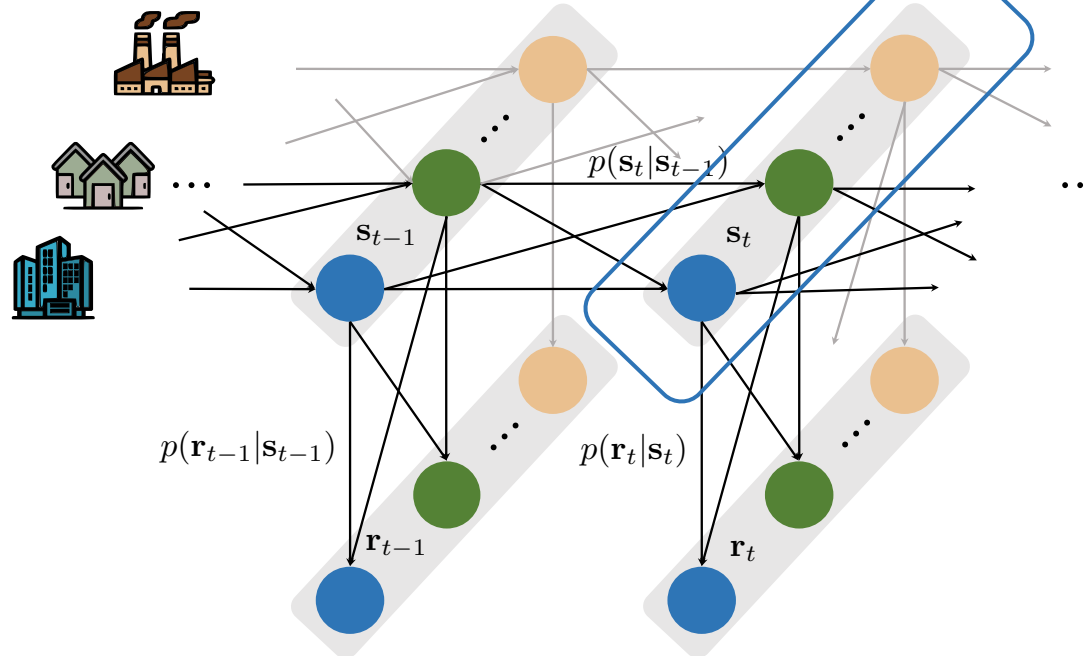
Hidden Markov Model characterized by the following Gaussian distributions:

$$p(\mathbf{s}_t | \mathbf{s}_{t-1}) = \mathcal{N}(\mathbf{s}_t; \mathbf{M}_{s,c} \mathbf{u}_s, \mathbf{\Sigma}_{s,c})$$

Loads

$$p(\mathbf{r}_t | \mathbf{s}_t) \propto p(\mathbf{s}_t | \mathbf{r}_t) = \mathcal{N}(\mathbf{s}_t; \mathbf{M}_{r,c} \mathbf{u}_r, \mathbf{\Sigma}_{r,c})$$

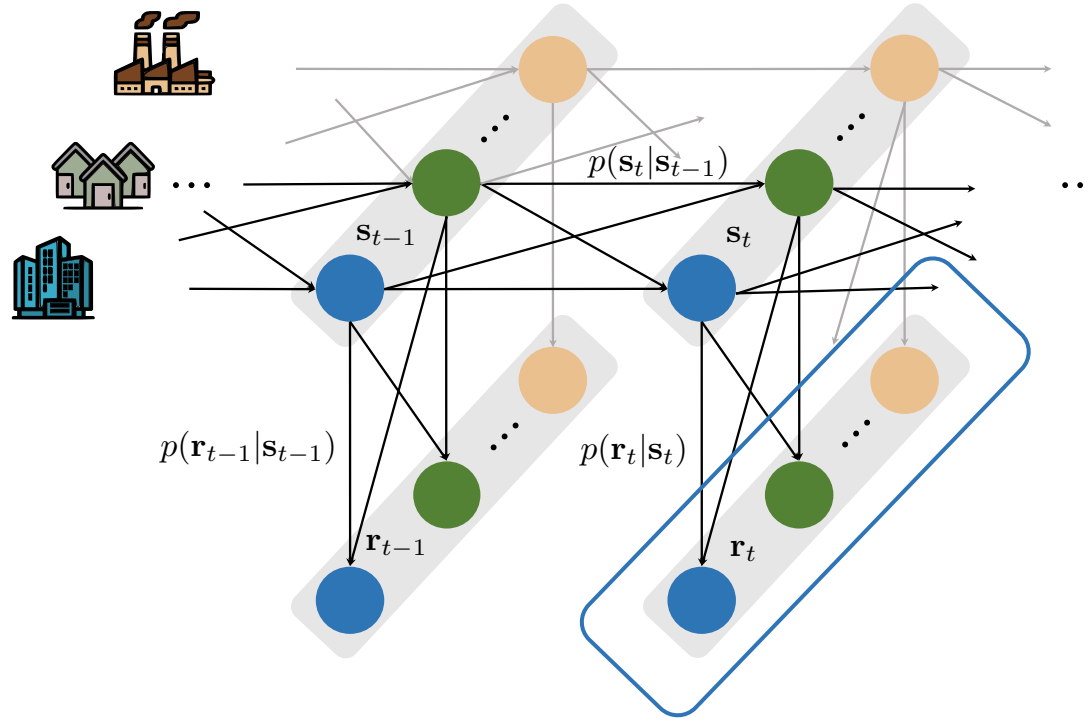
Observations



Multi-task Hidden Markov model

Hidden Markov Model characterized by the following Gaussian distributions:

$$p(\mathbf{s}_t | \mathbf{s}_{t-1}) = \mathcal{N}(\mathbf{s}_t; \mathbf{M}_{s,c} \mathbf{u}_s, \mathbf{\Sigma}_{s,c}) \quad \text{Loads}$$
$$p(\mathbf{r}_t | \mathbf{s}_t) \propto p(\mathbf{s}_t | \mathbf{r}_t) = \mathcal{N}(\mathbf{s}_t; \mathbf{M}_{r,c} \mathbf{u}_r, \mathbf{\Sigma}_{r,c}) \quad \text{Observations}$$



Multi-task Hidden Markov model

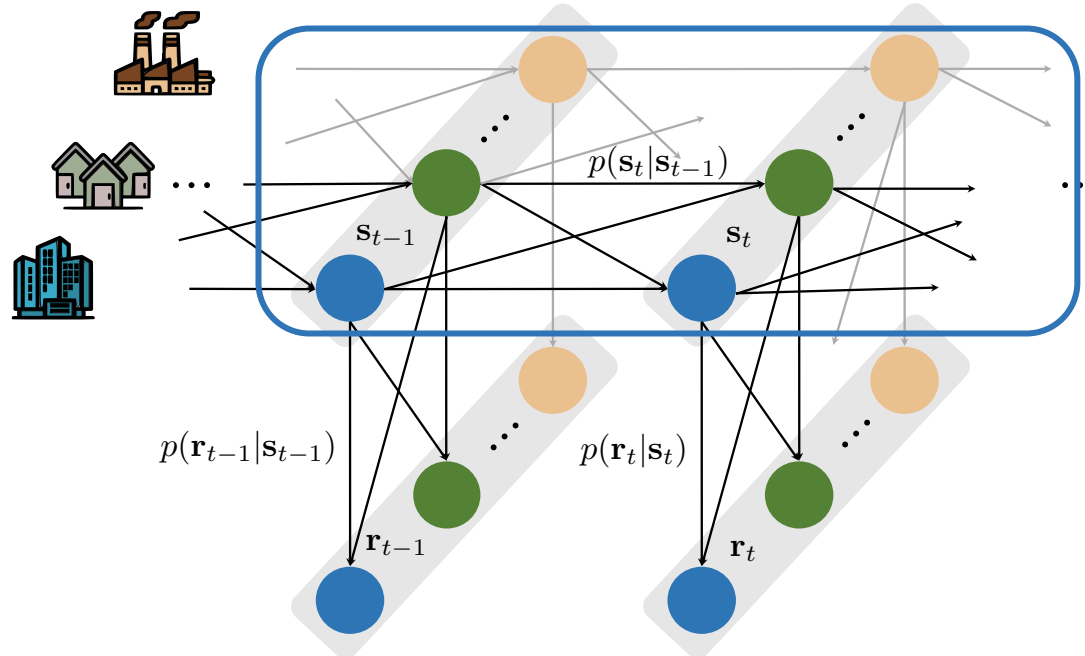
Hidden Markov Model characterized by the following Gaussian distributions:

$$p(\mathbf{s}_t | \mathbf{s}_{t-1}) = \mathcal{N}(\mathbf{s}_t; \mathbf{M}_{s,c} \mathbf{u}_s, \mathbf{\Sigma}_{s,c})$$

Loads

$$p(\mathbf{r}_t | \mathbf{s}_t) \propto p(\mathbf{s}_t | \mathbf{r}_t) = \mathcal{N}(\mathbf{s}_t; \mathbf{M}_{r,c} \mathbf{u}_r, \mathbf{\Sigma}_{r,c})$$

Observations



Multi-task Hidden Markov model

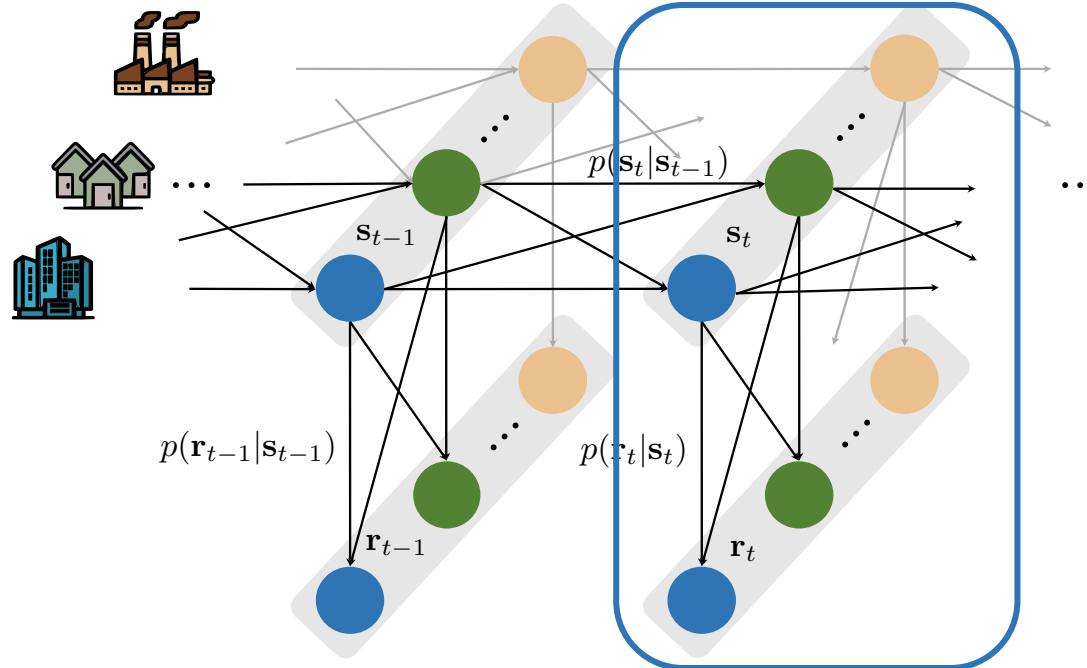
Hidden Markov Model characterized by the following Gaussian distributions:

$$p(\mathbf{s}_t | \mathbf{s}_{t-1}) = \mathcal{N}(\mathbf{s}_t; \mathbf{M}_{s,c} \mathbf{u}_s, \mathbf{\Sigma}_{s,c})$$

Loads

$$p(\mathbf{r}_t | \mathbf{s}_t) \propto p(\mathbf{s}_t | \mathbf{r}_t) = \mathcal{N}(\mathbf{s}_t; \mathbf{M}_{r,c} \mathbf{u}_r, \mathbf{\Sigma}_{r,c})$$

Observations

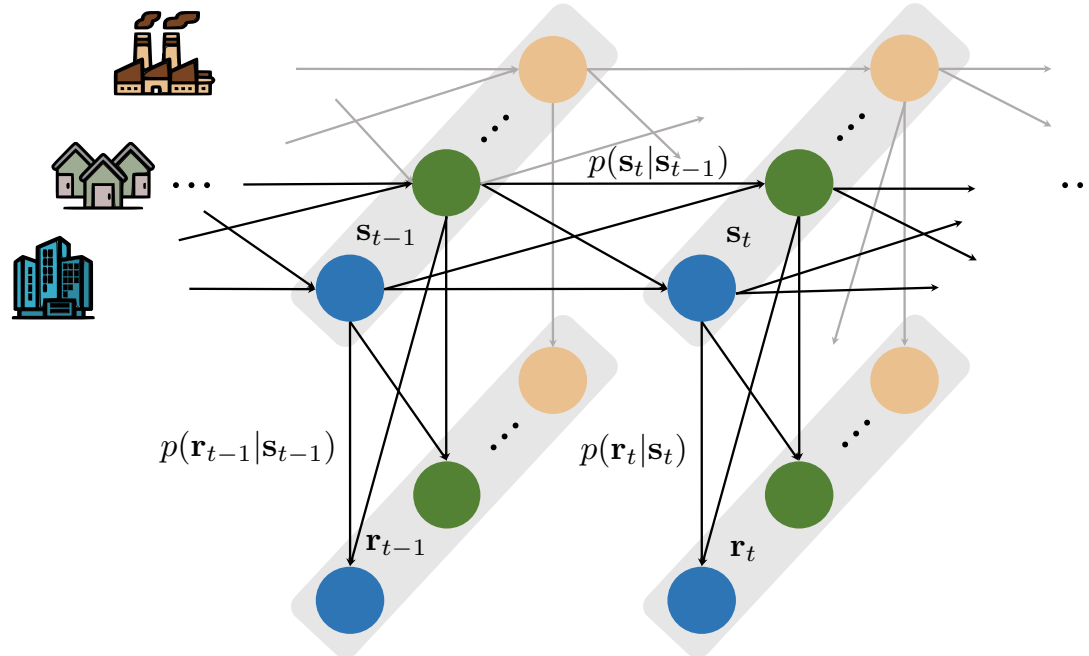


Multi-task Hidden Markov model

Hidden Markov Model characterized by the following Gaussian distributions:

$$p(\mathbf{s}_t | \mathbf{s}_{t-1}) = \mathcal{N}(\mathbf{s}_t; \mathbf{M}_{s,c} \mathbf{u}_s, \boldsymbol{\Sigma}_{s,c}) \quad \text{Loads}$$

$$p(\mathbf{r}_t | \mathbf{s}_t) \propto p(\mathbf{s}_t | \mathbf{r}_t) = \mathcal{N}(\mathbf{s}_t; \mathbf{M}_{r,c} \mathbf{u}_r, \boldsymbol{\Sigma}_{r,c}) \quad \text{Observations}$$



The calendar variable describes time factors that may affect load demand

$$c(t) \in \{1, \dots, C\}$$

Online learning of multi-task HMM parameters

Hidden Markov Model characterized by the following Gaussian distributions:

$$p(\mathbf{s}_t | \mathbf{s}_{t-1}) = \mathcal{N}(\mathbf{s}_t; \mathbf{M}_{s,c} \mathbf{u}_s, \boldsymbol{\Sigma}_{s,c})$$
$$p(\mathbf{r}_t | \mathbf{s}_t) \propto p(\mathbf{s}_t | \mathbf{r}_t) = \mathcal{N}(\mathbf{s}_t; \mathbf{M}_{r,c} \mathbf{u}_r, \boldsymbol{\Sigma}_{r,c})$$

Parameters $\mathbf{M}_{s,c}$, $\boldsymbol{\Sigma}_{s,c}$, $\mathbf{M}_{r,c}$ and $\boldsymbol{\Sigma}_{r,c}$ are given by recursions

$$\mathbf{M}_i = \mathbf{M}_{i-1} + \frac{(\mathbf{s}_{t_i} - \mathbf{M}_{i-1} \mathbf{u}_{t_i}) \mathbf{u}_{t_i}^\top \mathbf{P}_{i-1}}{\lambda + \mathbf{u}_{t_i}^\top \mathbf{P}_{i-1} \mathbf{u}_{t_i}}$$

$$\boldsymbol{\Sigma}_i = \boldsymbol{\Sigma}_{i-1} - \frac{1}{\gamma_i} \left(\boldsymbol{\Sigma}_{i-1} - \frac{\lambda^2 (\mathbf{s}_{t_i} - \mathbf{M}_{i-1} \mathbf{u}_{t_i}) (\mathbf{s}_{t_i} - \mathbf{M}_{i-1} \mathbf{u}_{t_i})^\top}{(\lambda + \mathbf{u}_{t_i}^\top \mathbf{P}_{i-1} \mathbf{u}_{t_i})^2} \right)$$

Online learning of multi-task HMM parameters

Hidden Markov Model characterized by the following Gaussian distributions:

$$p(\mathbf{s}_t | \mathbf{s}_{t-1}) = \mathcal{N}(\mathbf{s}_t; \mathbf{M}_{s,c} \mathbf{u}_s, \boldsymbol{\Sigma}_{s,c})$$
$$p(\mathbf{r}_t | \mathbf{s}_t) \propto p(\mathbf{s}_t | \mathbf{r}_t) = \mathcal{N}(\mathbf{s}_t; \mathbf{M}_{r,c} \mathbf{u}_r, \boldsymbol{\Sigma}_{r,c})$$

Parameters $\mathbf{M}_{s,c}$, $\boldsymbol{\Sigma}_{s,c}$, $\mathbf{M}_{r,c}$ and $\boldsymbol{\Sigma}_{r,c}$ are given by recursions

$$\mathbf{M}_i = \boxed{\mathbf{M}_{i-1}} + \frac{(\mathbf{s}_{t_i} - \mathbf{M}_{i-1} \mathbf{u}_{t_i}) \mathbf{u}_{t_i}^\top \mathbf{P}_{i-1}}{\lambda + \mathbf{u}_{t_i}^\top \mathbf{P}_{i-1} \mathbf{u}_{t_i}}$$

$$\boldsymbol{\Sigma}_i = \boxed{\boldsymbol{\Sigma}_{i-1}} - \frac{1}{\gamma_i} \left(\boxed{\boldsymbol{\Sigma}_{i-1}} - \frac{\lambda^2 (\mathbf{s}_{t_i} - \mathbf{M}_{i-1} \mathbf{u}_{t_i}) (\mathbf{s}_{t_i} - \mathbf{M}_{i-1} \mathbf{u}_{t_i})^\top}{(\lambda + \mathbf{u}_{t_i}^\top \mathbf{P}_{i-1} \mathbf{u}_{t_i})^2} \right)$$

Online learning of multi-task HMM parameters

Hidden Markov Model characterized by the following Gaussian distributions:

$$p(\mathbf{s}_t | \mathbf{s}_{t-1}) = \mathcal{N}(\mathbf{s}_t; \mathbf{M}_{s,c} \mathbf{u}_s, \boldsymbol{\Sigma}_{s,c})$$
$$p(\mathbf{r}_t | \mathbf{s}_t) \propto p(\mathbf{s}_t | \mathbf{r}_t) = \mathcal{N}(\mathbf{s}_t; \mathbf{M}_{r,c} \mathbf{u}_r, \boldsymbol{\Sigma}_{r,c})$$

Parameters $\mathbf{M}_{s,c}$, $\boldsymbol{\Sigma}_{s,c}$, $\mathbf{M}_{r,c}$ and $\boldsymbol{\Sigma}_{r,c}$ are given by recursions

$$\mathbf{M}_i = \boxed{\mathbf{M}_{i-1}} + \frac{(\mathbf{s}_{t_i} - \mathbf{M}_{i-1} \mathbf{u}_{t_i}) \mathbf{u}_{t_i}^\top \mathbf{P}_{i-1}}{\lambda + \mathbf{u}_{t_i}^\top \mathbf{P}_{i-1} \mathbf{u}_{t_i}}$$

$$\boldsymbol{\Sigma}_i = \boxed{\boldsymbol{\Sigma}_{i-1}} - \frac{1}{\gamma_i} \left(\boxed{\boldsymbol{\Sigma}_{i-1}} - \frac{\lambda^2 (\mathbf{s}_{t_i} - \mathbf{M}_{i-1} \mathbf{u}_{t_i}) (\mathbf{s}_{t_i} - \mathbf{M}_{i-1} \mathbf{u}_{t_i})^\top}{(\lambda + \mathbf{u}_{t_i}^\top \mathbf{P}_{i-1} \mathbf{u}_{t_i})^2} \right)$$

Multi-task probabilistic forecasting

Using the most recent learned parameters of the HMM we can provide probabilistic forecasts

$$p(\mathbf{s}_{t+i} | \mathbf{s}_t, \mathbf{r}_{t+1:t+i}) = \mathcal{N}(\mathbf{s}_{t+i}; \hat{\mathbf{s}}_{t+i}, \hat{\mathbf{E}}_{t+i}) \quad i = 1, 2, \dots, L$$

Multi-task probabilistic forecasting

Using the most recent learned parameters of the HMM we can provide probabilistic forecasts

$$p(\mathbf{s}_{t+i} | \mathbf{s}_t, \mathbf{r}_{t+1:t+i}) = \mathcal{N}(\mathbf{s}_{t+i}; \hat{\mathbf{s}}_{t+i}, \hat{\mathbf{E}}_{t+i}) \quad i = 1, 2, \dots, L$$

Multi-task probabilistic forecasting

Using the most recent learned parameters of the HMM we can provide probabilistic forecasts

$$p(\mathbf{s}_{t+i} | \mathbf{s}_t, \mathbf{r}_{t+1:t+i}) = \mathcal{N}(\mathbf{s}_{t+i}; \hat{\mathbf{s}}_{t+i}, \hat{\mathbf{E}}_{t+i}) \quad i = 1, 2, \dots, L$$

where $\hat{\mathbf{s}}_{t+i}$ and $\hat{\mathbf{E}}_{t+i}$ can be computed using the following recursions

$$\hat{\mathbf{s}}_{t+i} = \mathbf{W}_1(\mathbf{W}_1 + \mathbf{W}_2)^{-1} \mathbf{M}_{r,c} \mathbf{u}_r + \mathbf{W}_2(\mathbf{W}_1 + \mathbf{W}_2)^{-1} \mathbf{M}_{s,c} \hat{\mathbf{u}}_s$$

$$\hat{\mathbf{E}}_{t+i} = \mathbf{W}_2(\mathbf{W}_1 + \mathbf{W}_2)^{-1} \mathbf{W}_1$$

with

$$\mathbf{W}_1 = \boldsymbol{\Sigma}_{s,c} + \mathbf{M}_{s,c} \mathbf{N} \hat{\mathbf{E}}_{t+i-1} (\mathbf{M}_{s,c} \mathbf{N})^\top$$

$$\mathbf{W}_2 = \boldsymbol{\Sigma}_{r,c}$$

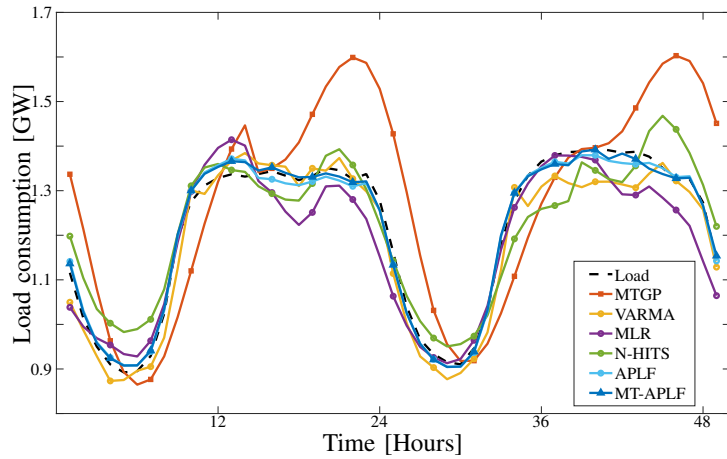
$$c = c(t+i), \hat{\mathbf{u}}_s = [1, \hat{\mathbf{s}}_{t+i-1}]^\top, \mathbf{u}_r = u_r(\mathbf{r}_{t+i})$$

$$\hat{\mathbf{s}}_t = \mathbf{s}_t, \hat{\mathbf{E}}_t = \mathbf{0}$$

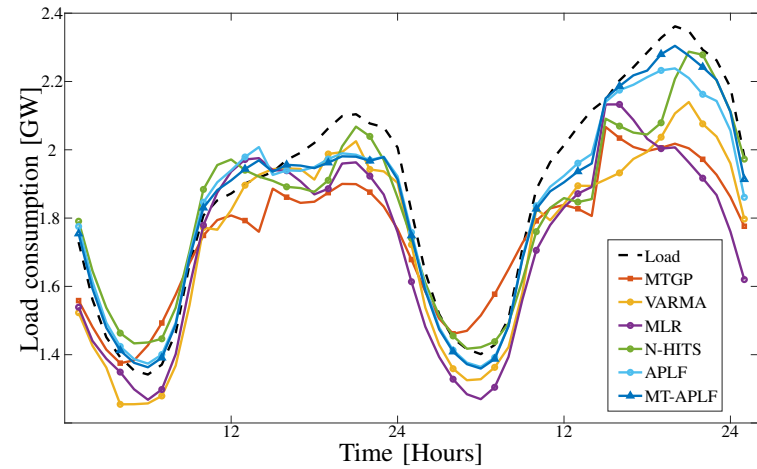
Outline

- Introduction and motivation
- Problem formulation
- Models and theoretical results
- Extension to high-dimensional models
- Experimental results

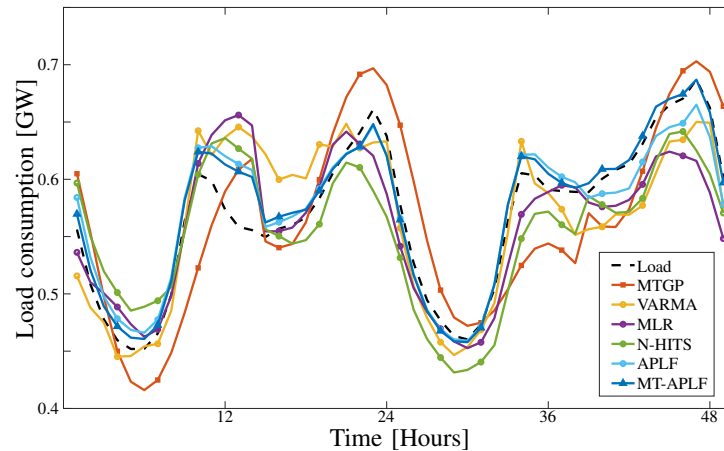
Prediction accuracy in 3 regions of New England



Maine



Vermont

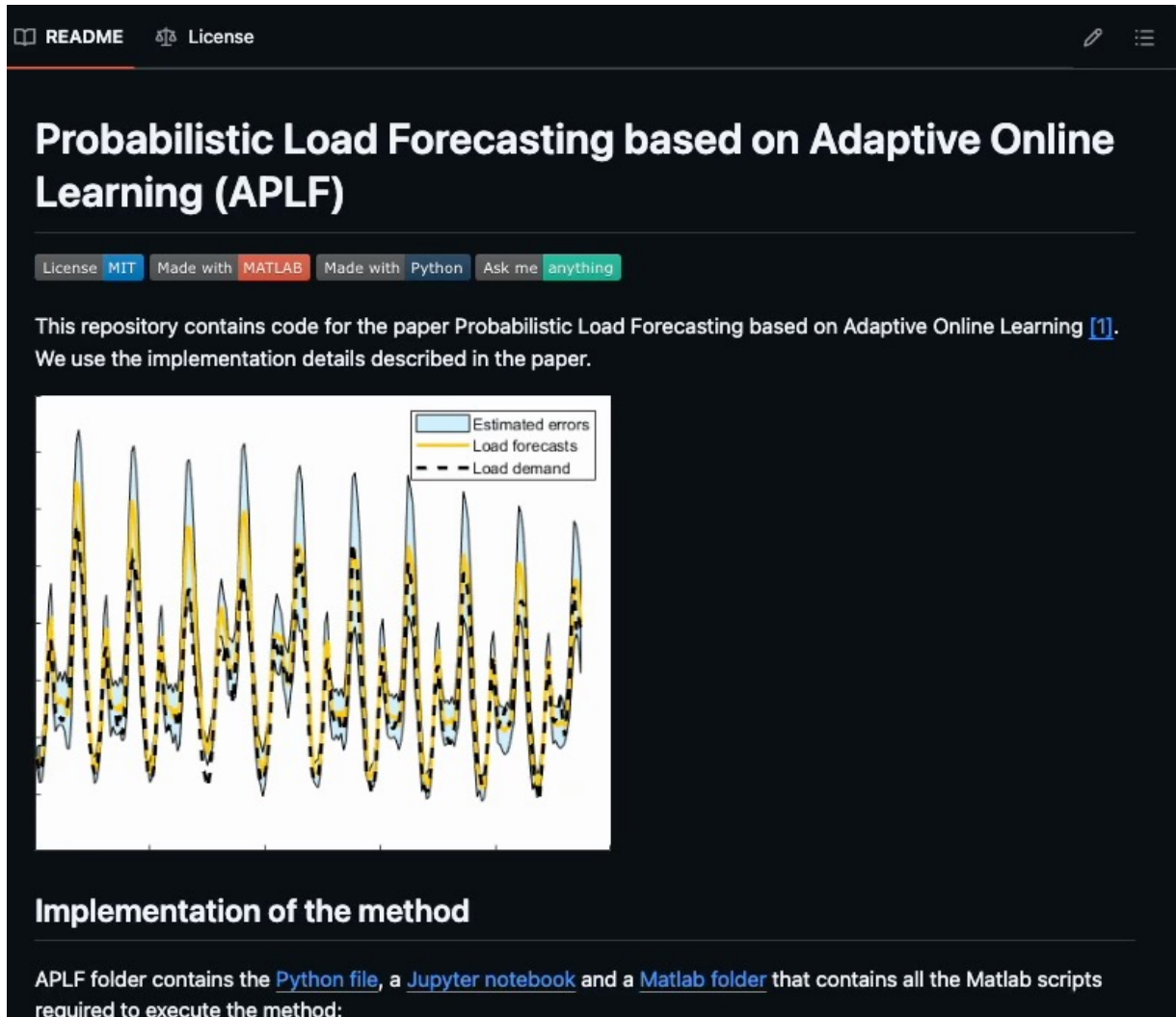


Western Massachusetts

Results

	APLF		MTGP		VAR		MLR		N-HITS		MT-APLF		
	MAPE	RMSE	MAPE	RMSE	MAPE	RMSE	MAPE	RMSE	MAPE	RMSE	MAPE	RMSE	
GEFCom2017	Entity 1	5.04	0.25	6.33	0.28	7.07	0.34	11.01	0.62	7.52	0.35	4.57	0.22
	Entity 2	3.18	0.05	4.55	0.07	5.28	0.09	6.87	0.13	4.77	0.07	3.04	0.05
	Entity 3	4.53	0.19	6.15	0.24	6.98	0.29	8.92	0.40	6.72	0.25	3.90	0.16
	Entity 4	4.29	0.08	5.95	0.01	6.97	0.13	9.83	0.21	6.52	0.11	3.73	0.07
	Entity 5	4.41	0.06	5.96	0.07	6.57	0.09	10.99	0.16	6.83	0.08	4.04	0.05
	Entity 6	5.15	0.12	6.34	0.14	7.03	0.17	12.75	0.35	7.16	0.16	4.43	0.10
	Entity 7	4.64	0.03	5.64	0.04	6.48	0.05	8.66	0.07	6.05	0.04	4.37	0.03
	Entity 8	4.86	0.13	6.43	0.16	7.18	0.19	9.63	0.29	6.29	0.16	4.06	0.10
	TOTAL	4.51	0.11	5.92	0.14	6.70	0.17	9.83	0.28	6.48	0.15	4.02	0.10
NewEngland	Entity 1	9.80	0.13	11.34	0.14	12.91	0.16	16.15	0.23	10.47	0.14	9.29	0.12
	Entity 2	5.58	0.09	6.81	0.10	7.44	0.11	11.50	0.20	7.32	0.11	5.11	0.08
	Entity 3	11.67	0.07	14.01	0.08	19.68	0.10	31.51	0.15	16.30	0.09	11.12	0.06
	Entity 4	5.52	0.23	6.95	0.29	7.63	0.32	12.72	0.61	7.33	0.31	5.34	0.22
	Entity 5	7.52	0.08	9.07	0.09	9.62	0.11	15.79	0.20	9.54	0.10	7.00	0.07
	Entity 6	6.16	0.12	7.63	0.15	8.85	0.17	14.81	0.34	8.36	0.16	6.00	0.12
	Entity 7	8.11	0.22	9.21	0.23	10.32	0.26	18.31	0.50	8.95	0.23	7.36	0.19
	Entity 8	4.71	0.16	6.03	0.21	6.93	0.24	11.41	0.42	6.42	0.22	4.47	0.15
	TOTAL	7.38	0.14	8.88	0.16	10.42	0.18	16.53	0.33	9.34	0.17	6.96	0.13
PJM	Entity 1	4.08	0.82	6.39	1.13	7.94	1.42	6.16	1.11	5.52	1.04	3.78	0.74
	Entity 2	5.25	0.95	8.47	1.24	9.20	1.15	7.21	0.97	6.41	0.99	4.48	0.69
	Entity 3	5.20	0.14	10.05	0.25	9.46	0.22	7.16	0.17	6.94	0.18	4.65	0.11
	Entity 4	5.10	0.20	7.44	0.27	9.20	0.34	7.32	0.27	6.79	0.27	4.72	0.18
	Entity 5	5.16	1.04	8.16	1.41	6.46	1.15	6.36	1.15	6.19	1.18	4.51	0.83
	Entity 6	4.26	0.09	5.43	0.11	6.44	0.12	6.41	0.13	5.48	0.11	4.12	0.08
	Entity 7	8.78	0.18	12.79	0.23	24.64	0.48	22.51	0.44	10.45	0.20	8.34	0.17
	Entity 8	4.01	0.44	10.37	1.00	6.62	0.63	5.80	0.59	5.34	0.54	3.66	0.37
	TOTAL	5.23	0.48	8.64	0.70	9.99	0.69	8.62	0.60	6.64	0.55	4.78	0.40

Github with the code and documentation



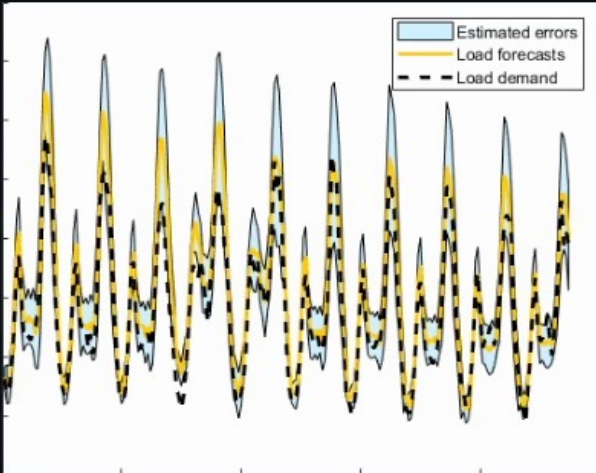
The screenshot shows a GitHub repository page with a dark theme. At the top, there are links for 'README' and 'License'. The main title is 'Probabilistic Load Forecasting based on Adaptive Online Learning (APLF)'. Below the title, there are badges for 'License MIT', 'Made with MATLAB', 'Made with Python', and 'Ask me anything'. The text below the badges reads: 'This repository contains code for the paper Probabilistic Load Forecasting based on Adaptive Online Learning [1]. We use the implementation details described in the paper.' Below this text is a line graph with a legend. The legend includes 'Estimated errors' (light blue area), 'Load forecasts' (yellow line), and 'Load demand' (black dashed line). The graph shows a highly oscillatory signal with a clear periodic pattern. Below the graph, the section 'Implementation of the method' is visible, followed by text describing the repository's structure: 'APLF folder contains the Python file, a Jupyter notebook and a Matlab folder that contains all the Matlab scripts required to execute the method:'.

README License

Probabilistic Load Forecasting based on Adaptive Online Learning (APLF)

License MIT Made with MATLAB Made with Python Ask me anything

This repository contains code for the paper Probabilistic Load Forecasting based on Adaptive Online Learning [1]. We use the implementation details described in the paper.



Implementation of the method

APLF folder contains the [Python file](#), a [Jupyter notebook](#) and a [Matlab folder](#) that contains all the Matlab scripts required to execute the method:



Outline

- Introduction and motivation
- Problem formulation
- Models and theoretical results
- Extension to high-dimensional models
- Experimental results
- Conclusions

Conclusions

- Proposed multi-task learning method can **learn the relationship** among multiple entities, **adapt to changes** in consumption patterns and **asses load uncertainties**.
- Parameters of the model are updated using a simple **recursive algorithm**, and the method provides **probabilistic predictions** with the most recent parameters
- Experimental results demonstrate that the proposed method achieves **higher performance** compared to existing multi-task learning techniques for load forecasting.